Abstract

A device for detecting moving objects present in the blind spot of a vehicle (1), the device having at least one object detection sensor (4), which, when the vehicle (1) is backed out of a parking space, detects the distance (d_n) between objects moving at an angle to the vehicle (1) and sends it to an evaluation unit (7), and the evaluation unit (7) determines the relative velocity (V_{rel}) from the distance (d_n) sent to it, and a warning device is switched on as a function of the distance (d_n) , the relative velocity (V_{rel}) and the velocity of the driver's vehicle (V_e) to notify the driver of the object (3) moving at an angle to the driver's vehicle (1).

(Figure 1)

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